Model fitting and goodness-of-fit for generalized linear models when covariates are interval-censored

Andrea Toloba Klaus Langohr Guadalupe Gómez Melis

Department of Statistics and Operations Research Universitat Politècnica de Catalunya-BarcelonaTech

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Overview

- 1. Interval-censored covariates
 - > What's interval censoring?
 - > Construction of the likelihood function
- 2. Parameter estimation

Gómez G, Espinal A and Lagakos SW (2003) Inference for a linear regression model with an interval-censored covariate. *Stat in Med*, 22(3), 409–425

- > Alternative approach that doesn't rely on discretization
- > In the context of GLMs
- 3. Goodness-of-fit
 - > Typical residuals for GLMs are not well-defined
 - > Extending definitions / exploring new residuals (work in progress)
- 4. Chromatography illustration

Interval censoring: Survival illustration

The time-to-event variable Z is interval-censored in $\lfloor Z_L, Z_R \rfloor$ if the exact value of Z is not observed, but it is known to lie within the time interval $|Z_L, Z_R|$.



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O Response variable: Time to breast retraction in early breast cancer patients

- Radiotherapy and adjuvant chemotherapy v.s. Radiotherapy alone
- Main goal: Effect of treatment in cosmetic appearance
- Cosmetic deterioration = manifestation of breast retraction
- Scheduled visits every 4 to 6 months



Beadle et al. (1984) Cosmetic results following primary radiation therapy for early breast cancer. Cancer, 54(12), 2911–2918

Interval censoring: Chromatography illustration

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Interval censoring: Chromatography illustration

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O Explanatory variable: Total plasma carotenoid concentration (Z)

- Carotenoids are a family of antioxidant compounds that we obtain from fruits and vegetables.
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Marhuenda-Muñoz M et al. (2022) Circulating carotenoids are associated with favorable lipid and fatty acid profiles in an older population at high cardiovascular risk. *Front Nutr*, 9, 967967

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Gómez Melis G, Marhuenda-Muñoz M and Langohr K (2022) Regression Analysis with Interval-Censored Covariates. Application to Liquid Chromatography. In: Sun J and Chen DG (eds) *Emerging Topics in Modeling Interval-Censored Survival Data* (pp. 271–294)

Generalized linear model

$$\mu = \mathsf{E}(Y|\mathbf{X}, \mathbf{Z}) = g^{-1}(\alpha + \boldsymbol{\beta}' \mathbf{X} + \boldsymbol{\gamma} \mathbf{Z})$$

where

- > $g(\cdot)$ monotonic differentiable link function
- > $X = (X_1, \ldots, X_p)'$ covariates
- > Z with distribution function $W(\cdot)$ and $Z \in [Z_L, Z_R]$
- > Y discrete or continuous, belonging to ψ -exponential family of distributions

$$f(y \mid \psi = \psi(\mu), \phi) = h(y, \phi) \exp[\{y\psi - a(\psi)\}/\phi]$$

> First two moments of Y: $\mu = \dot{a}(\psi)$ and $Var(Y \mid \mathbf{X}, Z) = \phi \ddot{a}(\psi)$

Goal: Estimate $\boldsymbol{\theta} = (\alpha, \boldsymbol{\beta}', \boldsymbol{\gamma}, \phi)'$ where ϕ represents the dispersion of the model.

Likelihood functions: full and simplified

$$L_{\text{full}} = \prod_{i=1}^{n} P(Y \in dy_i, \boldsymbol{X} \in d\boldsymbol{x}_i, Z_i \in [z_{l_i}, z_{r_i}], Z_L \in dz_{l_i}, Z_R \in dz_{r_i})$$

Likelihood functions: full and simplified

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$$L_{simp}(\boldsymbol{\theta}, W(\cdot)) = \prod_{i=1}^{n} P\left(Y \in dy_{i}, \boldsymbol{X} \in d\boldsymbol{x}_{i}, Z_{i} \in [z_{l_{i}}, z_{r_{i}}]\right)$$
$$= \prod_{i=1}^{n} \int_{z_{l_{i}}}^{z_{r_{i}}} f_{Y|\boldsymbol{X},Z}(y_{i} \mid \boldsymbol{x}_{i}, s; \boldsymbol{\theta}) dW(s \mid \boldsymbol{x}_{i}) P(\boldsymbol{X} \in d\boldsymbol{x}_{i}) ds$$
$$\propto \prod_{i=1}^{n} \int_{z_{l_{i}}}^{z_{r_{i}}} f_{Y|\boldsymbol{X},Z}(y_{i} \mid \boldsymbol{x}_{i}, s; \boldsymbol{\theta}) dW(s)$$

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$$\propto \prod_{i=1}^{n} \int_{z_{l_i}}^{z_{r_i}} f_{Y|\boldsymbol{X}, Z}(y_i \mid \boldsymbol{x}_i, s; \boldsymbol{\theta}) dW(s)$$

Assumptions for $L_{\rm simp} \propto L_{\rm full}$:

> Non-informative censoring ^[1]

$$dW(z \mid Z_L = z_l, Z_R = z_r) = \frac{dW(z)}{P(z_l \le Z \le z_r)}$$

> Y and (Z_L, Z_R) conditional independent given Z

^[1]Oller R, Gómez Melis G and Calle ML (2004) Interval censoring: model characterizations for the validity of the simplified likelihood. *Can J Stat*, 32(3), 315–326

Observations y_i provide crucial information about \widehat{W}



Parameter estimation: an EM-type algorithm

Maximization of

$$l(\boldsymbol{\theta}, W(\cdot)) = \sum_{i=1}^{n} \log \left\{ \int_{z_{l_i}}^{z_{r_i}} f(y_i \mid \boldsymbol{x_i}, s; \boldsymbol{\theta}) \, dW(s) \right\}$$

 $\text{over } \pmb{\theta} \in \mathbb{R}^{p+2} \times \mathbb{R}^+ \quad \text{ and } \quad W: \Omega \subseteq \mathbb{R} \to [0,1] \text{ distribution function}.$

- > Set up initial conditions and iterate between the maximization of l with respect to W and θ .
- > Differentiating the functional $l(W \mid \theta)$ and equating to zero yields the self-consistent equations in A).
- > The EM-type algorithm is defined by

$$\widehat{W}(z_0) = \frac{1}{n} \sum_{i=1}^n \frac{\int_{z_{l_i}}^{z_{r_i}} f(y_i \mid \boldsymbol{x_i}, s; \, \widehat{\boldsymbol{\theta}}) \, dW(s \wedge z_0)}{\int_{z_{l_i}}^{z_{r_i}} f(y_i \mid \boldsymbol{x_i}, s; \, \widehat{\boldsymbol{\theta}}) \, dW(s)}$$

$$\widehat{\boldsymbol{\theta}} = \operatorname{argmax}_{\boldsymbol{\theta}} \sum_{i=1}^n \log \left\{ \int_{z_{l_i}}^{z_{r_i}} f(y_i \mid \boldsymbol{x_i}, s; \, \boldsymbol{\theta}) \, d\widehat{W}(s) \right\}$$

where $s \wedge z_0 = \min\{s, z_0\}.$

Parameter estimation: construction of partition intervals

$$l(\boldsymbol{\theta}, W(\cdot)) = \sum_{i=1}^{n} \log \left\{ \int_{z_{l_i}}^{z_{r_i}} f(y_i \mid \boldsymbol{x_i}, s; \boldsymbol{\theta}) \, dW(s) \right\}$$

Parameter estimation: construction of partition intervals

 $\{I_j\}_{j=1}^{m_n}$ is a partition of the support $\Omega = [0, z_{r_5}]$ such that

$$l(\boldsymbol{\theta}, W(\cdot)) = \sum_{i=1}^{n} \log \left\{ \sum_{j=1}^{m_n} \kappa_j^i \int_{I_j} f(y_i \mid \boldsymbol{x_i}, s; \boldsymbol{\theta}) \, dW(s) \right\}$$

where $\kappa_j^i = \mathbb{1}\{I_j \subseteq \lfloor z_{l_i}, z_{r_i} \rfloor\}.$

Parameter estimation: redefinition of the maximization problem

- > Assume W is uniform in I_j for all $j = 1, \ldots, m_n$.
- > Then the maximization problem rewrites to

$$l(\boldsymbol{\theta}, \boldsymbol{w}) = \sum_{i=1}^{n} \log \left\{ \sum_{j=1}^{m_n} \kappa_j^i \frac{\hat{w}_j}{|I_j|} \int_{I_j} f(y_i \mid \boldsymbol{x}_i, s; \boldsymbol{\theta}) ds \right\}$$

where $|I_j|$ denotes the length of I_j ,

over $\boldsymbol{\theta} \in \mathbb{R}^{p+2} \times \mathbb{R}^+$ and \boldsymbol{w} s.t. $\sum^{m_n} w_j = 1$ and $w_j \ge 0$.

> And the EM-type algorithm $(j = 1, ..., m_n)$:

$$(A) \quad w_j^{(l+1)} = \frac{1}{n} \sum_{i=1}^n \kappa_j^i \quad \frac{\frac{w_j^{(l)}}{|I_j|} \int_{I_j} f(y_i \mid s; \hat{\theta}) ds}{\sum_{k=1}^{m_n} \kappa_k^i \quad \frac{w_k^{(l)}}{|I_k|} \int_{I_k} f(y_i \mid s; \hat{\theta}) ds}$$

$$(B) \quad \hat{\theta} = \operatorname{argmax} l(\theta \mid \hat{w})$$

Solved by Limited-memory Broyden–Fletcher–Goldfarb–Shanno (L-BFGS) algorithm, a quasi-Newton method for the numerical search of local maxima.

Diagnostics for GLM assumptions: Pearson and deviance residuals

> Pearson residuals are defined as $r_i^{(P)} = (y_i - \hat{\mu}_i)/\sqrt{V(\hat{\mu}_i)}$, where $V(\cdot)$ is the variance function in $Var(Y_i) = \phi V(\mu_i)$. Asymptotic normality of $r_i^{(P)}$ follows from the Central Limit Theorem (CLT) applied to Y_i .

Asymptotics for Pearson residuals in case of $Y_i \sim \text{Gamma}$ with shape ν and scale $\lambda_i = \mu_i / \nu$. $Y_i = \sum_{k=1}^{\nu} U_k \text{ with } U_k \sim_{i.i.d.} \text{Exp}(1/\lambda_i)$

By the CLT, the Pearson residual $\sqrt{\nu} \frac{y_i - \hat{\mu}_i}{\sqrt{\hat{\mu}_i^2}} \rightarrow_d N(0, 1)$ as $\nu \rightarrow \infty$. For the *i*th Pearson residual to be asymp. normal, the data dispersion $\phi = 1/\nu$ should be low.

> Deviance residuals are defined as $r_i^{(D)} = \operatorname{sgn}(y_i - \hat{\mu}_i)\sqrt{d(y_i, \hat{\mu}_i)}$, where $d(y_i, \hat{\mu}_i) = 2 \left\{ y_i \left(\psi(y_i) - \psi(\hat{\mu}_i) \right) - b(\psi(y_i)) + b(\psi(\hat{\mu}_i)) \right\}$ is the unit deviance. Asymptotic normality derives from the saddle-point approximation of Y_i 's distribution to the normal.

> Discard Pearson and deviance residuals because their asymptotics are approximations that, in most cases, do not hold.^[2]

^[2]Smyth GK and Dunn PK (2018) Generalized Linear Models With Examples in R. Section 8.6.

Diagnostics for GLM assumptions: Quantile residuals

In the context of a GLM defined by $E[Y \mid \mathbf{X}_i, Z_i] = \mu_i = g^{-1}(\alpha + \beta' \mathbf{X}_i + \gamma Z_i)$, with predicted mean $\hat{\mu}_i = g^{-1}(\hat{\alpha} + \hat{\beta}' \mathbf{X}_i + \hat{\gamma} z_i)$,

Quantile residuals are defined by

$$r_i = \Phi^{-1}(F(y_i; \hat{\mu}_i, \hat{\phi})),$$

where Φ is the cdf of the standard Normal distribution.

- > Consider a gamma GLM with $\phi = 1$ fitted to data
- > Observation with y = 1.2 and $\hat{\mu} = 3$



Smyth GK and Dunn PK (2018) Generalized Linear Models With Examples in R. Section 8.3.4

Diagnostics for the distributional assumption

- > Denote by F^* the true distribution of Y_i . Then $U_i = F^*(y_i) \sim U(0,1)$.
- > Quantile residuals are normally distributed if $F(\cdot; \hat{\mu}_i, \hat{\phi})$ is good enough for each i.
- $> F(y_i; \hat{\mu}_i, \hat{\phi}) = F(y_i \mid X = \boldsymbol{x_i}, Z = z_i; \hat{\alpha}, \hat{\beta}, \hat{\gamma}, \hat{\phi}), \text{ so we define}$ $r_i = \Phi^{-1}(F(y_i \mid \boldsymbol{x_i}, Z_i \in |z_{l_i}, z_{r_i}|; \hat{\alpha}, \hat{\beta}, \hat{\gamma}, \hat{\phi}))$

$$= \Phi^{-1}(E_{Z_i}[F(y_i; \hat{\mu}_i, \hat{\phi}) \mid z_{l_i}, z_{r_i}])$$

- > It is defined under the true distribution of Z_i . We choose to estimate r_i assuming that Z_i is uniformly distributed within $\lfloor z_{l_i}, z_{r_i} \rfloor$.
- Simulation analysis to assess the power of these residuals in validating the distribution assumption.

Next steps

- > Possible improvements of the estimation algorithm
 - \Box Alternatives to the assumption of W being uniform in I_j
 - Elaborate a B step analogous to IRLS to improve computational efficiency
 - \Box Kuhn–Tucker conditions to check that \widehat{W} is a global maximum
- > Check consistency of the estimator $\hat{ heta}$
- > Derive standard error and confidence intervals for $\hat{ heta}$
- > Adapt diagnostic tools for GLM assumptions
 - ☑ Quantile residuals to check the distributional assumption
 - Working residuals^[3] to check the linearity of covariates and link function assumptions
 - \Box Outliers / influential observations (Cook's distance^[3])

If everything goes as planned, we'll be publishing by the end of September!

Chromatography illustration

Marhuenda-Muñoz M et al. (2022) Circulating carotenoids are associated with favorable lipid and fatty acid profiles in an older population at high cardiovascular risk. *Front Nutr*, 9, 967967

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Total plasma carotenoid concentration (Z)

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 $E[g|ucose] = g^{-1}(\alpha + \gamma \cdot \text{Total plasma carotenoid concentration})$



> Y has right-skewed distribution $\rightarrow g = \log$ i.e. assume Z_i is related to Y_i in log scale $E[Y_i \mid Z_i] = \exp\{\alpha + \gamma Z_i\}$

> $Y_i \mid Z_i$ Gamma or Gaussian distributed Gaussian $\rightarrow Var(Y_i \mid Z_i) = \phi$ Gamma $\rightarrow Var(Y_i \mid Z_i) = \phi \mu_i^2$

Estimation results

 $E[glucose] = g^{-1}(\alpha + \gamma \cdot Carotenoid \text{ concentration})$

Regression parameters:

	$\hat{\alpha}$	$\hat{\gamma}$	$\hat{\phi}$
Gaussian	4.76	-0.009	720
Gamma	4.76	-0.008	0.043

The distinction is on the variance:

Gaussian $\rightarrow \operatorname{Var}(Y \mid Z_i) = 720$ Gamma $\rightarrow \operatorname{Var}(Y \mid Z_i) \in [312, 584]$ The resulting \widehat{W} under both models:



$$\begin{split} & \text{For } z \in I_k = \lfloor q_j, p_j \rfloor, \\ & \widehat{W}(z) = \sum_{I_j \prec I_k} \hat{w}_j + \hat{w}_k \, \frac{z - q_k}{p_k - q_k} \end{split}$$

> Mean glucose levels decrease 0.9% for each unit increase in total plasma carotenoid concentration $(E[Y \mid z + 1] = e^{\hat{\gamma}} \times E[Y \mid z]).$

> From interval-censored measurements, the model is able to identify the non-parametric estimator distribution of W.

Quantile residuals

For each model and individual *i*,

$$\begin{aligned} r_i &= \Phi^{-1}(F(y_i \mid \boldsymbol{x}_i, Z_i \in \lfloor z_{l_i}, z_{r_i} \rfloor; \hat{\alpha}, \hat{\boldsymbol{\beta}}, \hat{\gamma}, \hat{\phi})) \\ &= \Phi^{-1}(E_{Z_i}[F(y_i; \hat{\mu}_i, \hat{\phi}) \mid z_{l_i}, z_{r_i}]) \end{aligned}$$

and $r_i \sim N(0, 1)$ if the distribution resembles the true one.





Summary

- We have developed an algorithm for modeling responses with interval-censored covariates that does not require prior knowledge of the covariate support.
- $\hat{\mathbf{v}}_{i}^{s}$ Essential: derive the standard error and asymptotic distribution to provide confidence intervals for $\hat{\theta}$.
- $\hat{\mathbf{x}}$ Desirable: proof for the consistency of $\hat{\boldsymbol{\theta}}$.
- Derived an R package to facilitate its use in applied research.